

# Spatially Combined Keyword Searches

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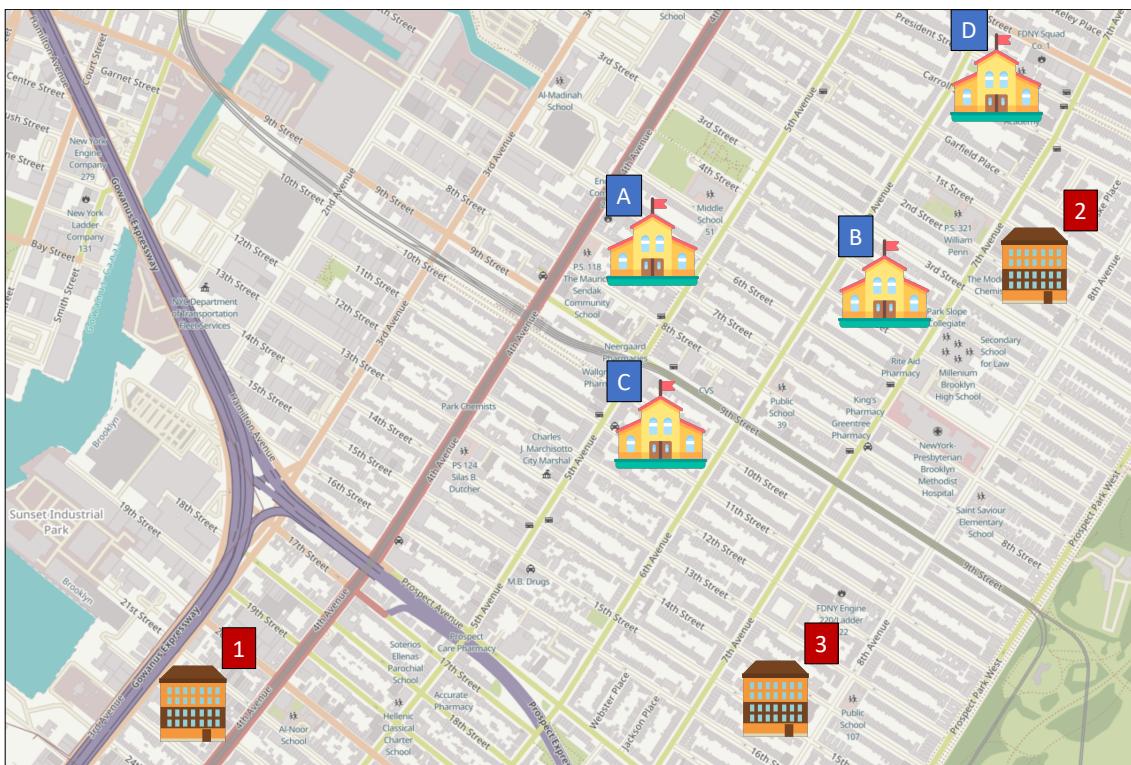
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# Motivation

apartments	amenities
1	balcony, pool, gym
2	balcony, gym
3	balcony, pool



kindergartens	description
A	German, indoor-playground
B	German, outdoor-playground
C	German, outdoor-playground
D	outdoor-playground

$$q = \{\Psi_{\text{apartments}}, \Psi_{\text{kindergartens}}, \epsilon\}$$

$$\Psi_{\text{apartments}} = \{\text{balcony, gym}\}$$

$$\Psi_{\text{kindergartens}} = \{\text{german, outdoor-playground}\}$$

$$\epsilon = 1\text{km}$$

$$\text{dist}(1, A) = 1.8\text{km}$$

$$\text{dist}(1, C) = 1.2\text{km}$$

$$\text{dist}(2, B) = 300\text{m}$$

$$\text{dist}(2, C) = 900\text{m}$$

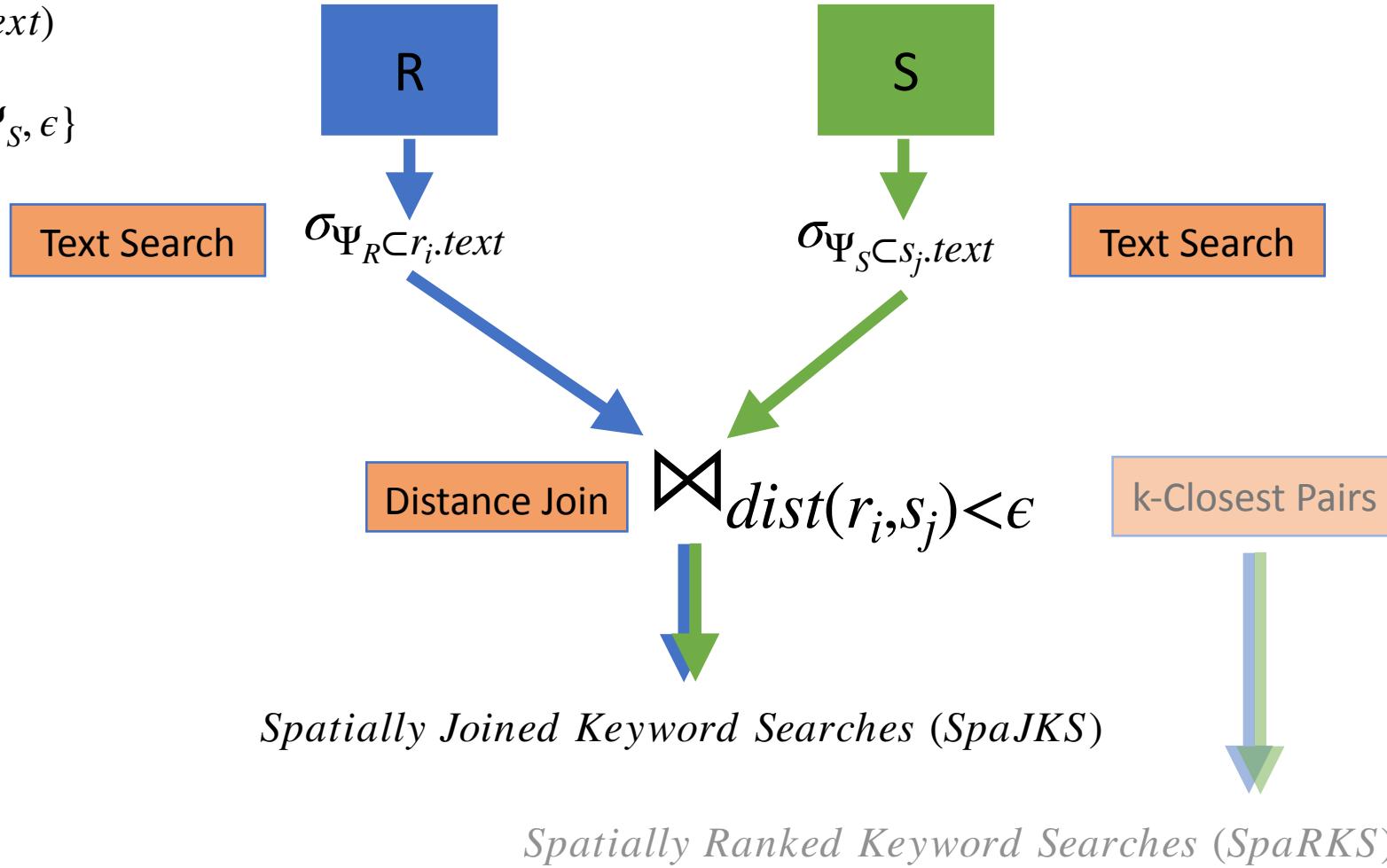
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- Problem definition
  - Evaluation strategies
    - Possible Indices
    - Text/Spatial First
    - Spatial/Spatio-textual Probing
    - Join Based
  - Experimental results

# Problem Definition

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$$r_i = (x, y, \text{text})$$

$$q = \{\Psi_R, \Psi_S, \epsilon\}$$



# Evaluation Strategies



Inverted File | R-Tree | IR-Tree[1] | Spatio-textual Grid [2]

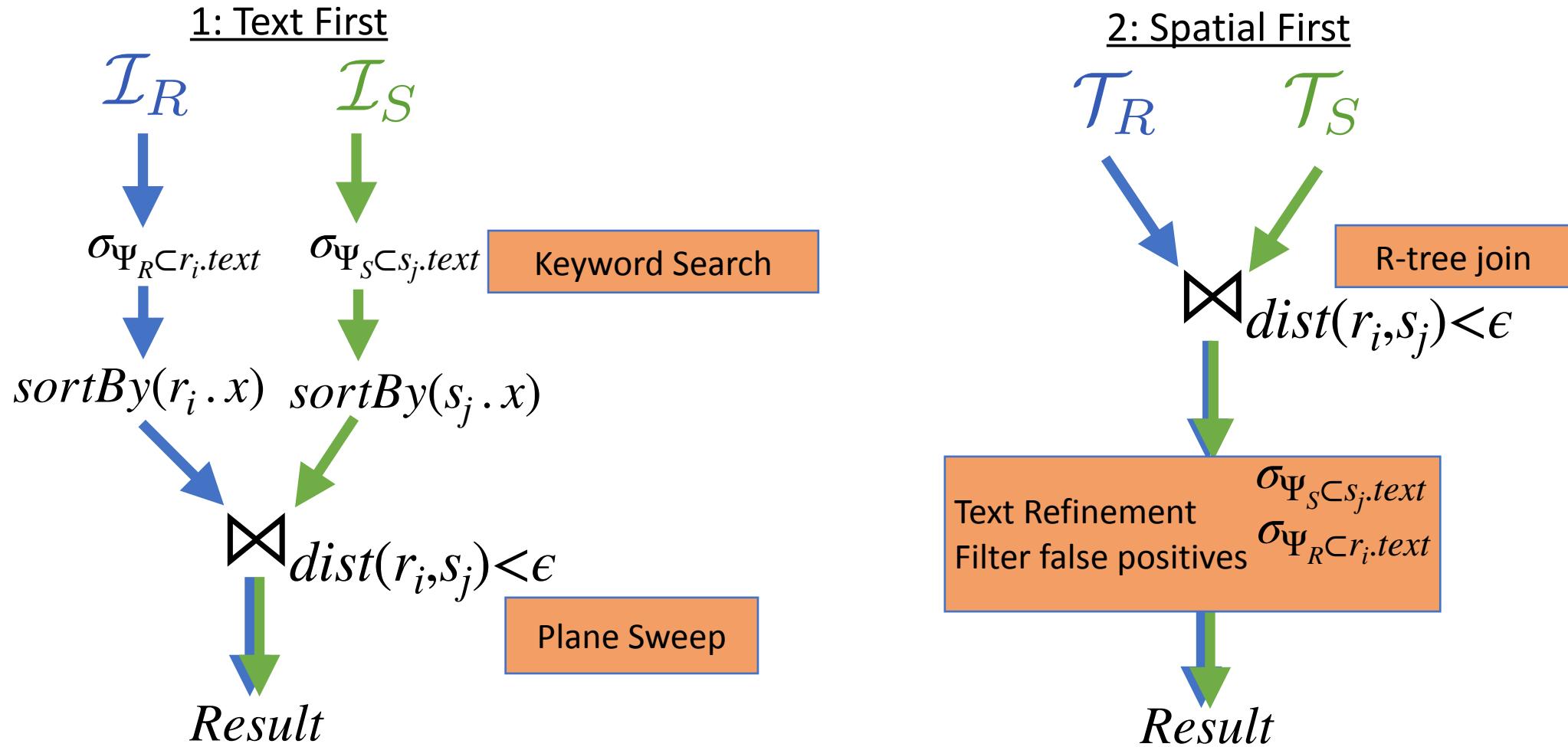
$\mathcal{I}$	$\mathcal{T}$	$\mathcal{H}$	$G$
$\mathcal{I}_R$	1: Text first		$\mathcal{I}_S$
$\mathcal{T}_R$	2: Spatial first		$\mathcal{T}_S$
$\mathcal{I}_R$	3: Spatial probing		$\mathcal{T}_S$
$\mathcal{I}_R$	4: Spatio-textual probing		$\mathcal{H}_S$
$\mathcal{H}_R$	5: IR-tree join		$\mathcal{H}_S$
$G_R$	6: Grid based join		$G_S$

[1] G. Cong, C. S. Jensen, and D. Wu. Efficient Retrieval of the Top-k Most Relevant Spatial Web Objects. Proc. VLDB Endow. 2, 1 (2009), 337–348.

[2] P. Bouros, S. Ge, and N. Mamoulis. Spatio-textual similarity joins. Proc. VLDB Endow. 6, 1 (2012), 1–12.

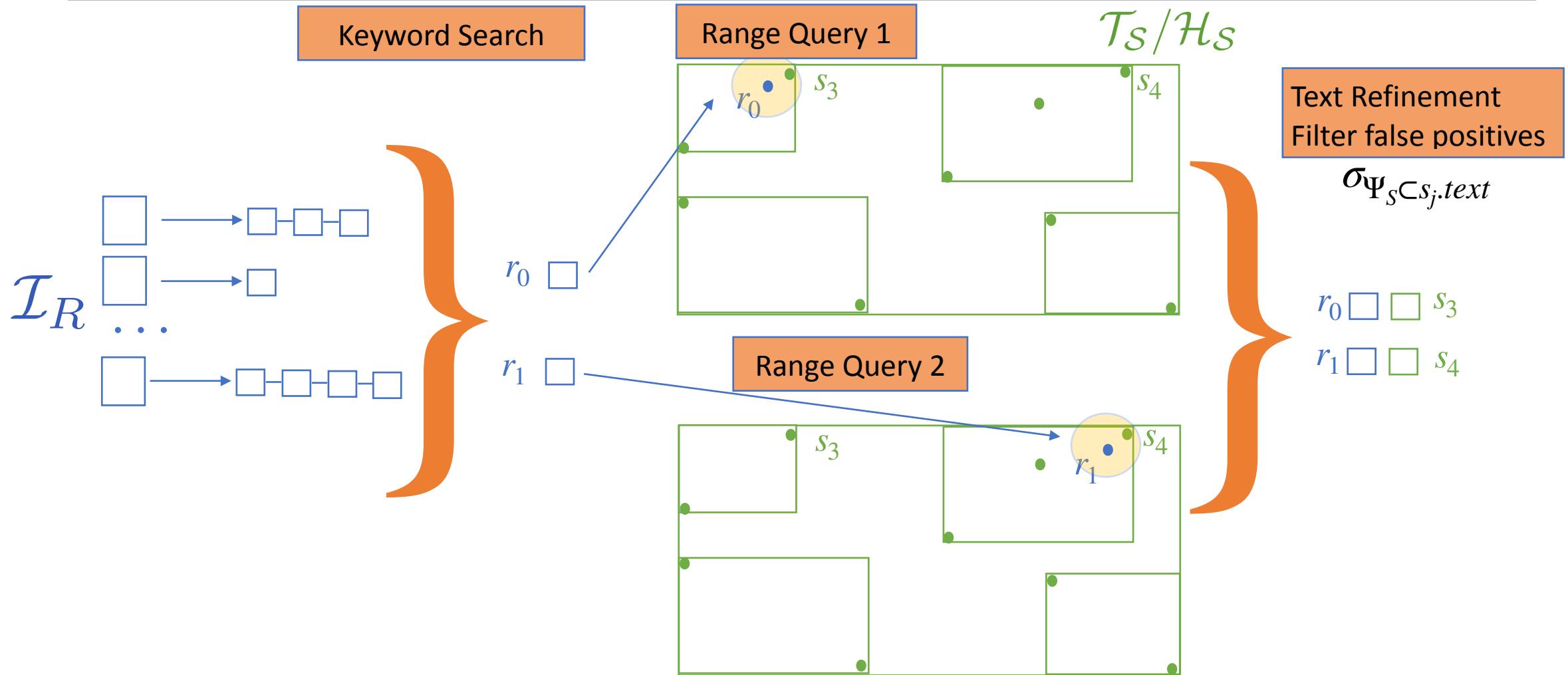
# 1/2: Text/Spatial First

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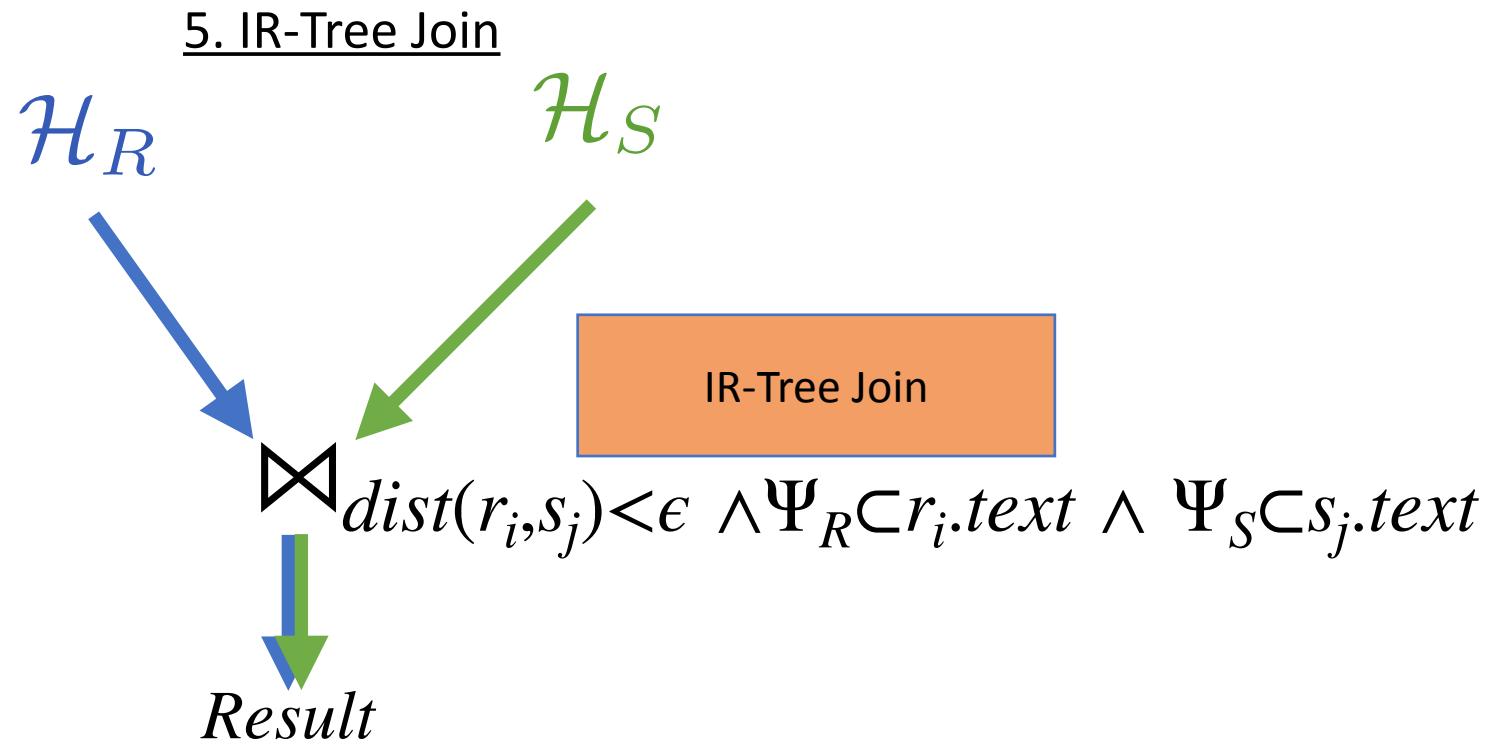
# 3/4: Spatial/Spatio-textual Probing

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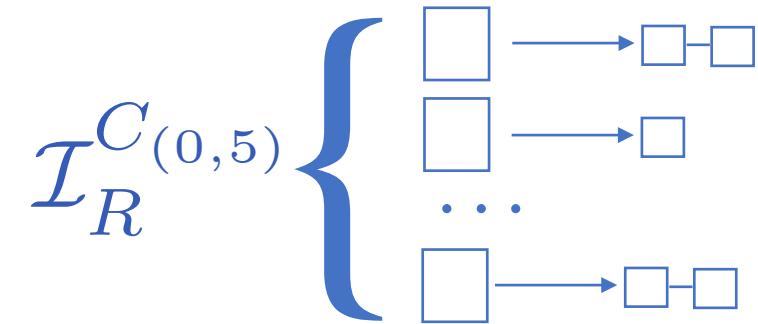
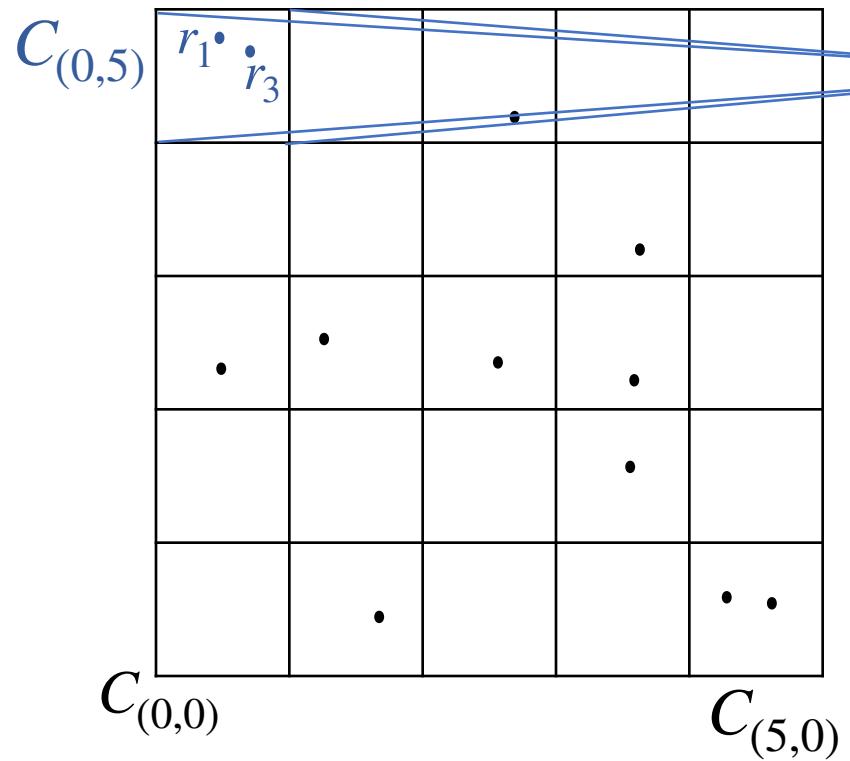


# 5: IR-Tree Join

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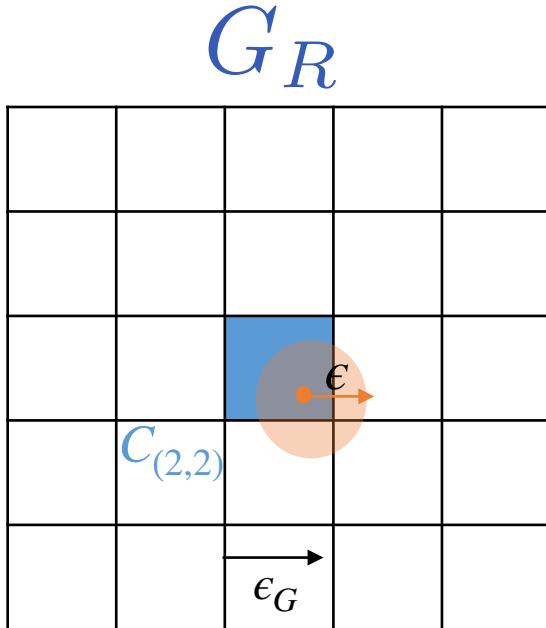


# 6: Spatio-Textual Grid

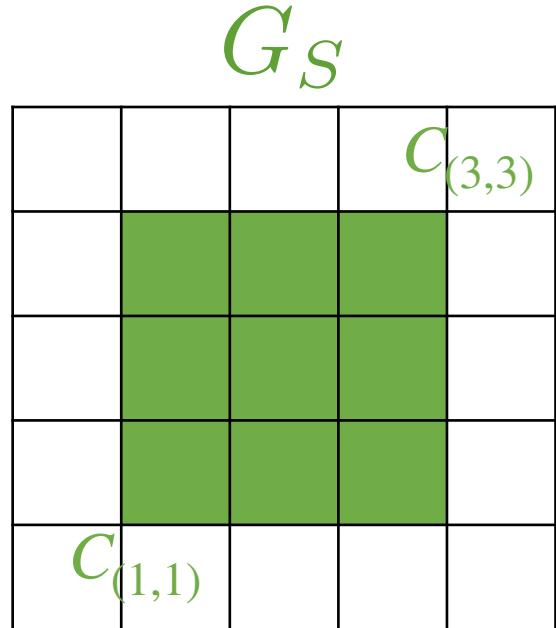


# 6: Grid-based Join

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$$\epsilon < \epsilon_G$$



- iterate over cells R
- identify join partner of S
- per pair -> test first

$$G_R^{C_{(3,3)}} \bowtie_{dist(r_i, s_j) < \epsilon} G_R^{C_{(1,1)}}$$

...

$$G_R^{C_{(3,3)}} \bowtie_{dist(r_i, s_j) < \epsilon} G_R^{C_{(3,3)}}$$

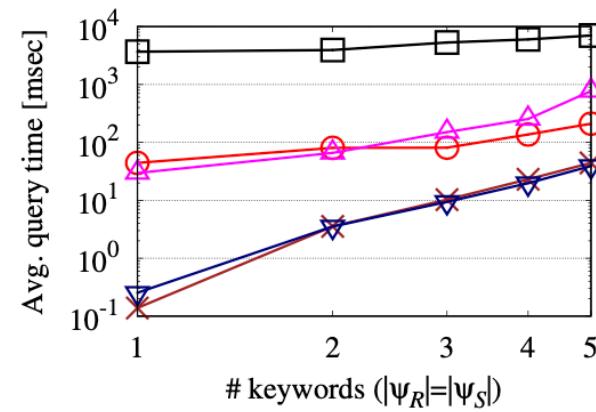
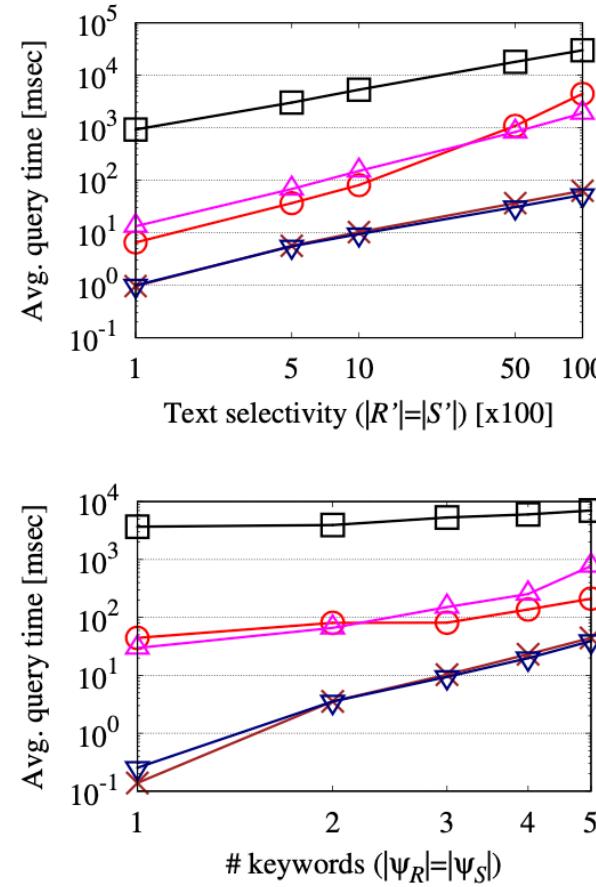
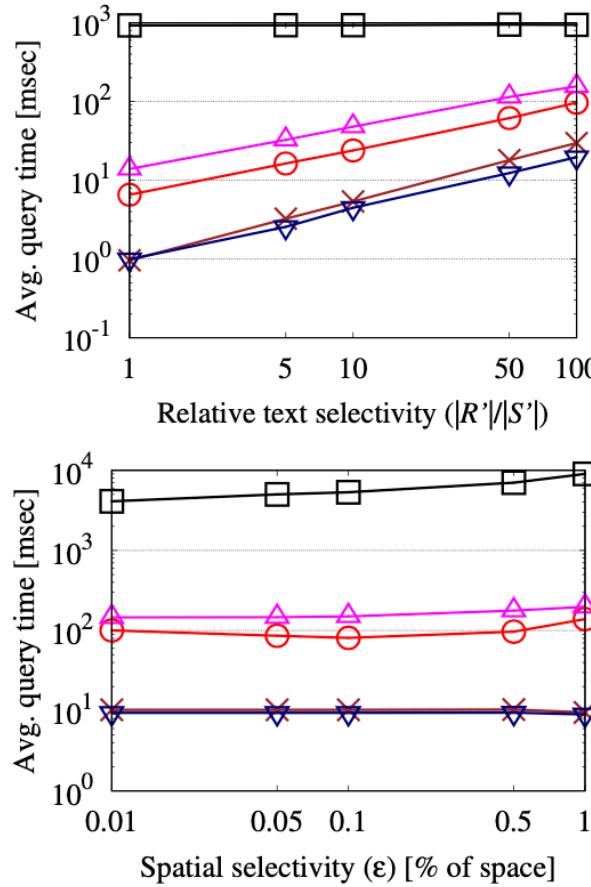
# Experiments



- Datasets
  - one real (polybot)[3]
  - multiple synthetic
- AVG response time when varying
  - spatial selectivity
  - text selectivity
  - number keywords
  - cardinality
  - ...

[3] M. Christoforaki, . He, C. Dimopoulos, A. Markowetz, and T. Suel. Text vs. space: efficient geo-search query processing. ACM CIKM 2009. 423–432.

# Experiments Polybot



3 tiers on response time:

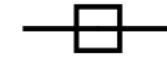
1. text first / grid join



2. spatio-textual probing/ IR-tree join



3. spatial-probing / spatial first



# To sum up

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- Contributions
    - new retrieval tasks
      - Spatially Joined Keyword Searches (SpaJKS)
      - Spatially Ranked Keyword Searches (SpaRKS)
  - Future work
    - multiple keyword searches
    - text search as similarity search